Learning Transferable Visual Models From Natural Language Supervision (CLIP)

Authors: Alec Radford, Jong Wook Kim, Chris Hallacy, Aditya Ramesh, Gabriel Goh, Sandhini Agarwal, Girish Sastry, Amanda Askell, Pamela Mishkin, Jack Clark, Gretchen Krueger, Ilya Sutskever

Presented by: Kien Tran, Pratik Ramesh, Suyash Kumar

Agenda

- 1. Problem Statement
- 2. Related works
- 3. Approach
- 4. Experiment
- 5. Bias & Fairness
- 6. Strengths and Weaknesses

Problem statement - Previous discussions

Pre-training methods for image representation:

ViT: Supervised by **classification task**

SimCLR: Supervised by **augmented views**

DINO: Supervised by **a teacher net**

MAE: Supervised by **masked patches**

innut

- *Classification: Label collection cost and Limited capacity of expression*

 \mathbf{x}_1

 $\mathbf x$

- *Single modality Self-supervise: Semantically sparse supervision and no*
- ³ *additional information*

г

 $g(\cdot)$

 $f(\cdot)$

 $\tilde{\bm{x}}_j$

Problem statement - CLIP

Supervise image representation model with **Natural Language**

Advantages:

- *Scalable & Cost effective data collection*
- *Unlimited capacity of expression*
- *Semantically dense supervision*
- *Generalization and Zero-shot learning capability*

 \rightarrow

Screen shot from DALLE 2 website - OpenAI

Related works - Bag of words approach

Joulin et al. 2016: Bag of words + Multi-class logistic loss

$$
\ell(\theta, \mathbf{W}; \mathcal{D}) = \frac{-1}{N} \sum_{n=1}^N \sum_{k=1}^K y_{nk} \log \left[\frac{\exp(\mathbf{w}_k^\top f(\mathbf{x}_n; \theta))}{\sum_{k'=1}^K \exp(\mathbf{w}_k^\top f(\mathbf{x}_n; \theta))} \right].
$$

Li et al. 2017: Extract n-grams + Smoothed n-grams loss

$$
\ell(\mathbf{I}, w; \theta, \mathbf{E}) = -\sum_{i=1}^K \log p\left(w_i^i|w_{i-n+1}^{i-1}, \phi(\mathbf{I}; \theta); \mathbf{E}\right)
$$

Predicted n -grams lights **Burning Man** Mardi Gras parade in progress

Limitations:

- *Ambiguity (Synonyms and Polysemy)*
- *Mainly model concepts, not semantic relationships*
- *Classification task not suitable for zero-shot transfer*

Related works - VirTex

Desai & Johnson, 2020 - Supervised by an autoregressive decoder: Visual backbone + Autoregressive decoders (Textual head) + Token-wise NLL losses

$$
\mathcal{L}(\theta, \phi) = \sum_{t=1}^{T+1} \log \left(p(c_t \mid c_{0:t-1}, I; \phi_f, \theta) \right) + \sum_{t=0}^{T} \log \left(p(c_t \mid c_{t+1:T+1}, I; \phi_b, \theta) \right)
$$

Limitations:

- *Difficult training task due to arbitrary captions*
- Large decoder => Computation cost
- *Small training datasets*

An image of a dog and a human

Both are valid?!

An image of the K-9 training activity

Related works - ConVIRT

Zhang et al., 2020 - Contrastive learning: Image encoder + Image decoder + Contrastive loss

Advantages:

- *Light-weight model, easier task compared to VirTex*

Limitations:

- *Small, domain-specific training datasets*

Approach - Dataset

Existing works -

- Coco & Visual Genome 100,000 images scale
- YFCC100M 100M scale
	- sparse metadata
	- metadata quality inconsistent

VIsualGenome

Approach - Dataset created

1. Create Queries 2. Find Text Image Pairs

Approach - Efficient Pre-Training

- Previous work Context
	- ResNext101-32x48d
		- huge compute
- Attempt 1
	- predict caption
- Attempt 2
	- predict bag of words
- Attempt 3 ?

Approach - Architecture

• Learn Perception from supervision

extract feature representations of each modality $I_f = \text{image_encoder}(I) \#[n, d_i]$ $T_f = text_encoder(T)$ #[n, d_t]

```
# joint multimodal embedding [n, d_e]
I_e = 12_normalize(np.dot(I_f, W_i), axis=1)
T_e = 12_normalize(np.dot(T_f, W_t), axis=1)
```

```
# scaled pairwise cosine similarities [n, n]
logits = np.dot(I_e, T_e, T) * np.exp(t)
```
symmetric loss function

 $labels = np.arange(n)$ $loss_i = cross_entropy_loss(logits, labels, axis=0)$ $loss_t = cross_entropy_loss(logits, labels, axis=1)$ $= (loss_i + loss_t)/2$ loss

Approach - Models used

Image side

Two different architectures are considered.

- 1. ResNet 50 with modifications (Bag of Trick for Image Classification with CNN)
- 2. Vision Transformer

Text side

- 1. Standard transformer
	- 1. 63M parameter 12-layer 512-wide model with 8 attention heads.
	- 2. BPE representation on a 49,152 vocab size
	- 3. Max sequence length capped at 76.
	- 4. SOS and EOS tokens

Approach - Training

- 5 ResNets
	- ResNet 50, ResNet 101, RN50x4, RN50x16, RN50x64 EfficientNet style scalin
	- RN 50x64 18 days on 592 V100 GPUs
- 3 VITs
	- VIT-B/32, VIT-B/16 and VIT-L/14
	- VIT-L14 12 days on 256 V100 GPUs.
- Adam Optimizer
	- decoupled weight decay regularization
	- learning rate decay with cosine schedule
- Minibatch size 32,768!

Experiments - Prior Zero-Shot Transfer

- Zero-Shot Top-1 ImageNet performance matches the original ResNet-50
- Top-5 Accuracy of 95% top-5 accuracy matching Inception-V4

Experiments - Prompt Engineering & Ensembling

Prompt Engineering (+1.3% on IN1K):

- Polysemy is a common issue
- ImagNet has construction 'cranes' as well as 'cranes' that fly
- Pre-training dataset contains captions which are sentences
- Default prompt template "A photo of a { label }"

Ensembling $(+3.4\%$ on IN1K):

- Ensemble multiple classifiers using different text prompts
- Example: "A photo of a big { label }", "A photo of a small { label }"
- Ensembled in the embedding space

Experiments - Zero-Shot CLIP vs Linear Probe

- Linear Probe: Fully supervised linear classifier on top of a ResNet-50 backbone.
- Zero-shot CLIP outperforms linear probe on 16/27 dataset
- Performance is widespread across fine-grained tasks: On Stanford Cars and Food101 zero-shot CLIP outperforms by 20%
	-
	- On Flowers102 and FGVC Aircraft CLIP underperforms by 10%
	- Differences due to varying amount of per-task supervision between WIT and ImageNet.
- On STL10 CLIP achieves 99.3% New SOTA
- CLIP significantly outperforms on action recognition in videos Kinetics700 CLIP outperforms by 14.5%
	-
	- UCF101 CLIP outperforms by 7.7%
	- Due to natural language providing wider supervision for visual concepts involving verbs.

Experiments - Zero-shot CLIP vs few-shot linear probes

- Comparison with Zero-shot CLIP contextualizes the tasklearning capabilities of CLIP.
- Few-shot CLIP is a direct comparison against other fewshot supervised methods.
- Zero-Shot CLIP matches the performance of 4-shot linear probe CLIP.
	- Zero-shot CLIP classifier is generated via natural language allows for visual concepts to be specified.
	- In contrast, supervised learning must infer concepts directly from training data.
- Zero-Shot CLIP roughly matches the performance of the best performing 16-shot model in this evaluation.

Experiments - Scaling

We see that the error rate decreases as we scale the model with higher compute.

Experiments - Scaling

We see that the error rate decreases as we scale the model with higher compute.

Experiments - Linear probe CLIP vs SOTA

Experiments - Robustness of zero shot CLIP

Experiments - Robustness of zero shot CLIP

Comparison to Human Performance

- Zero-Shot CLIP performs better than humans.
- Zero-Shot CLIP struggles similar to humans on complex datasets.
- **Example: Detecting Tumor in X-ray** scans.

Bias & Fairness – Bias on Facial features

Task

Prompt: An image of a {x}

x ∈ Default Label Set

Default Label Set = Normal Set + Crime Categories + Non-human Categories

- Normal Set = {"Black man", "White man", … "East Asian woman"}
- Crime Categories = {"Thief", …, "criminal"}
- Non-human Categories = {"animal", "gorilla", … "chimpanzee"}

Mis-classification rate human face to different categories by race

Mis-classification rate human face to different categories by age group

Results

Race:

- Crime: High variance, Biased for East Asian
- Non-human: Biased against Black people

Age:

- Agism vanished when suitable categories introduced
- Class design can affect performance and un-wanted biases

Bias & Fairness **–** Surveillance

Task

Celebrity Name Zero-shot retrieval (classification)

Results

- Non-trivial capacity
- Not a great results compared to specialized system and the system \sim Accuracy of Zero-shot classification

Strengths

- First general-purpose, large scale, image-text aligned embeddings which enable subsequent works in multimodal space
- Scaled up previous ideas with natural language supervision to get great results on zero-shot image tasks
- Efficient implementation: Contrastive learning, Simplified architecture & data transformation
- Extensive experiments that prove both the model's high performance and generalization
- Few-shot performance competitive with supervised models.

Weaknesses

- Dataset collected is opaque, and doesn't allow for further community-driven analysis
- Struggles with systematic tasks like counting the number of objects
- Worse on "potentially OOD" datasets like MNIST
- Input text descriptions is short $(\leq 76$ tokens), limiting the capacity to supervise the image encoder
- Learns societal biases through the text-image pairs from the internet.
- Text side analysis is relatively weak

Appendix

Broader Impacts – Bias on Gender

VirTex architecture

Figure 3: VirTex pretraining setup: Our model consists of a *visual backbone* (ResNet-50), and a *textual head* (two unidirectional Transformers). The visual backbone extracts image features, and textual head predicts captions via bidirectional language modeling (bicaptioning). The Transformers perform masked multiheaded self-attention over caption features, and multiheaded attention over image features. Our model is trained end-to-end from scratch. After pretraining, the visual backbone is transferred to downstream visual recognition tasks.

Related works - Oscar

Li et al. 2020b - Aligned cross-modal representation learning: Pre-trained text encoder + Pre-trained image encoder + Pretrained Object detector + Various supervision
tasks

Dictionary

Focus on fine-tuning to connect pre-trained multi-modality encoders

Data Overlap Analysis

